

# **Texts in Computational Science and Engineering**

**6**

## Editors

Timothy J. Barth

Michael Griebel

David E. Keyes

Risto M. Nieminen

Dirk Roose

Tamar Schlick

More information about this series at <http://www.springer.com/series/5151>

Hans Petter Langtangen

# A Primer on Scientific Programming with Python

5th Edition



Springer

Hans Petter Langtangen  
Simula Research Laboratory  
Fornebu, Norway

On leave from:

Department of Informatics  
University of Oslo  
Oslo, Norway

ISSN 1611-0994

Texts in Computational Science and Engineering

ISBN 978-3-662-49886-6

ISBN 978-3-662-49887-3 (eBook)

DOI 10.1007/978-3-662-49887-3

Springer Heidelberg Dordrecht London New York

Library of Congress Control Number: 2016945366

Mathematic Subject Classification to (2010): 26-01, 34A05, 34A30, 34A34, 39-01, 40-01, 65D15, 65D25, 65D30, 68-01, 68N01, 68N19, 68N30, 70-01, 92D25, 97-04, 97U50

© Springer-Verlag Berlin Heidelberg 2009, 2011, 2012, 2014, 2016

This work is subject to copyright. All rights are reserved by the Publisher, whether the whole or part of the material is concerned, specifically the rights of translation, reprinting, reuse of illustrations, recitation, broadcasting, reproduction on microfilms or in any other physical way, and transmission or information storage and retrieval, electronic adaptation, computer software, or by similar or dissimilar methodology now known or hereafter developed.

The use of general descriptive names, registered names, trademarks, service marks, etc. in this publication does not imply, even in the absence of a specific statement, that such names are exempt from the relevant protective laws and regulations and therefore free for general use.

The publisher, the authors and the editors are safe to assume that the advice and information in this book are believed to be true and accurate at the date of publication. Neither the publisher nor the authors or the editors give a warranty, express or implied, with respect to the material contained herein or for any errors or omissions that may have been made.

Printed on acid-free paper

This Springer imprint is published by Springer Nature  
The registered company is Springer Berlin Heidelberg

---

## Preface

The aim of this book is to teach computer programming using examples from mathematics and the natural sciences. We have chosen to use the Python programming language because it combines remarkable expressive power with very clean, simple, and compact syntax. Python is easy to learn and very well suited for an introduction to computer programming. Python is also quite similar to MATLAB and a good language for doing mathematical computing. It is easy to combine Python with compiled languages, like Fortran, C, and C++, which are widely used languages for scientific computations.

The examples in this book integrate programming with applications to mathematics, physics, biology, and finance. The reader is expected to have knowledge of basic one-variable calculus as taught in mathematics-intensive programs in high schools. It is certainly an advantage to take a university calculus course in parallel, preferably containing both classical and numerical aspects of calculus. Although not strictly required, a background in high school physics makes many of the examples more meaningful.

Many introductory programming books are quite compact and focus on listing functionality of a programming language. However, learning to program is learning how to *think* as a programmer. This book has its main focus on the thinking process, or equivalently: programming as a problem solving technique. That is why most of the pages are devoted to case studies in programming, where we define a problem and explain how to create the corresponding program. New constructions and programming styles (what we could call theory) is also usually introduced via examples. Particular attention is paid to verification of programs and to finding errors. These topics are very demanding for mathematical software, because the unavoidable numerical approximation errors are possibly mixed with programming mistakes.

By studying the many examples in the book, I hope readers will learn how to think right and thereby write programs in a quicker and more reliable way. Remember, nobody can learn programming by just reading – one has to solve a large amount of exercises hands on. The book is therefore full of exercises of various types: modifications of existing examples, completely new problems, or debugging of given programs.

To work with this book, I recommend using Python version 2.7. For Chaps. 5–9 and Appendices A–E, you need the NumPy and Matplotlib packages, preferably

also the IPython and SciTools packages, and for Appendix G, Cython is required. Other packages used in the text are nose and sympy. Section H.1 has more information on how you can get access to Python and the mentioned packages.

There is a web page associated with this book, <http://hplgit.github.io/sciprimer>, containing all the example programs from the book as well as information on installation of the software on various platforms.

**Python version 2 or 3?** A common problem among Python programmers is to choose between version 2 or 3, which at the time of this writing means choosing between version 2.7 and 3.5. A common recommendation is to go for Python 3, because this is the version that will be further developed in the future. However, there is a problem that much useful mathematical software in Python has not yet been ported to Python 3. Therefore, Python version 2.7 is the most popular version for doing scientific computing, and that is why also this book applies version 2.7.

A widely used strategy for software developers who want to write Python code that works with both versions, is to develop a common version for Python 2 and 3. For the programs in this book, a common version can easily be produced by first developing for version 2.7 and then *automatically* convert the code by running the `futurize` program. Section 4.10 demonstrates how this is done in simple cases.

The Python 2.7 code in this book sticks to all modern constructions that are backported from version 3 such that the code becomes as close as possible to the equivalent Python 3 code. At any time, you can just run `futurize` to see the differences between your Python 2.7 version and the corresponding Python 3.5 version.

**Contents** Chapter 1 introduces variables, objects, modules, and text formatting through examples concerning evaluation of mathematical formulas. Chapter 2 presents programming with `while` and `for` loops as well as lists, including nested lists. The next chapter deals with two other fundamental concepts in programming: functions and `if-else` tests.

How to read data into programs and deal with errors in input are the subjects of Chap. 4. Chapter 5 introduces arrays and array computing (including vectorization) and how this is used for plotting  $y = f(x)$  curves and making animation of curves. Many of the examples in the first five chapters are strongly related. Typically, formulas from the first chapter are used to produce tables of numbers in the second chapter. Then the formulas are encapsulated in functions in the third chapter. In the next chapter, the input to the functions are fetched from the command line, and validity checks of the input are added. The formulas are then shown as graphs in Chap. 5. After having studied Chaps. 1–5, the reader should have enough knowledge of programming to solve mathematical problems by what many refer to as “MATLAB-style” programming.

Chapter 6 explains how to work with dictionaries and strings, especially for interpreting text data in files and storing the extracted information in flexible data structures. Class programming, including user-defined types for mathematical computations (with overloaded operators), is introduced in Chap. 7. Chapter 8 deals with random numbers and statistical computing with applications to games and random walks. Object-oriented programming, in the meaning of class hierarchies and inheritance, is the subject of Chap. 9. The key examples here deal with building toolkits for numerical differentiation and integration as well as graphics.

Appendix A introduces mathematical modeling, using sequences and difference equations. Only programming concepts from Chaps. 1–5 are used in this appendix, the aim being to consolidate basic programming knowledge and apply it to mathematical problems. Some important mathematical topics are introduced via difference equations in a simple way: Newton’s method, Taylor series, inverse functions, and dynamical systems.

Appendix B deals with functions on a mesh, numerical differentiation, and numerical integration. A simple introduction to ordinary differential equations and their numerical treatment is provided in Appendix C. Appendix D shows how a complete project in physics can be solved by mathematical modeling, numerical methods, and programming elements from Chaps. 1–5. This project is a good example on problem solving in computational science, where it is necessary to integrate physics, mathematics, numerics, and computer science.

How to create software for solving ordinary differential equations, using both function-based and object-oriented programming, is the subject of Appendix E. The material in this appendix brings together many parts of the book in the context of physical applications and differential equations.

Appendix F is devoted to the art of debugging, and in fact problem solving in general. Speeding up numerical computations in Python by migrating code to C via Cython is exemplified in Appendix G. Finally, Appendix H deals with various more advanced technical topics.

Most of the examples and exercises in this book are quite short. However, many of the exercises are related, and together they form larger projects, for example on Fourier Series (3.21, 4.21, 4.22, 5.41, 5.42), numerical integration (3.11, 3.12, 5.49, 5.50, A.12), Taylor series (3.37, 5.32, 5.39, A.14, A.15, 7.23), piecewise constant functions (3.29–3.33, 5.34, 5.47, 5.48, 7.19–7.21), inverse functions (E.17–E.20), falling objects (E.8, E.9, E.38, E.39), oscillatory population growth (A.19, A.21, A.22, A.23), epidemic disease modeling (E.41–E.48), optimization and finance (A.24, 8.42, 8.43), statistics and probability (4.24, 4.25, 8.23, 8.24), hazard games (8.8–8.14), random walk and statistical physics (8.32–8.40), noisy data analysis (8.44–8.46), numerical methods (5.25–5.27, 7.8, 7.9, A.9, 7.22, 9.15–9.17, E.30–E.37), building a calculus calculator (7.34, 9.18, 9.19), and creating a toolkit for simulating vibrating engineering systems (E.50–E.55).

Chapters 1–9 together with Appendices A and E have from 2007 formed the core of an introductory first semester bachelor course on scientific programming at the University of Oslo (INF1100, 10 ECTS credits).

**Changes from the fourth to the fifth edition** Substantial changes were introduced in the fourth edition, and the fifth edition is primarily a consolidation of those changes. Many typos have been corrected and many explanations and exercises have been improved. The emphasis on unit tests and test functions, especially in exercises, is stronger than in the previous edition. Symbolic computation with the aid of SymPy is used to a larger extent and integrated with numerical computing throughout the book. All classes are now new-style (instead of old-style/classic as in previous editions). Examples on Matplotlib do not use the pylab module anymore, but pyplot and MATLAB-like syntax is still favored to ease the transition between Python and MATLAB. The concept of closures is more explicit than in earlier editions (see the new Sect. 7.1.7) since this is a handy and popular construc-

tion much used in the scientific Python community. We also discuss the difference between Python 2 and 3 and demonstrate how to use the `future` module to write code that runs under both versions.

The most substantial new material in the fifth edition appears toward the end of Chap. 5 and regards high-performance computing, linear algebra, and visualization of scalar and vector fields. Although this material is not used elsewhere in the book, many readers have requested basic recipes when going from one to two variables or from vectors to matrices later when solving more advanced problems and using the book as their programming reference. The new material in Chap. 5 was written jointly with Dr. Øyvind Ryan.

**Acknowledgments** This book was born out of stimulating discussions with my close colleague Aslak Tveito, and he started writing what is now Appendix B and C. The whole book project and the associated university course were critically dependent on Aslak’s enthusiastic role back in 2007. The continuous support from Aslak regarding my book projects is much appreciated and contributes greatly to my strong motivation. Another key contributor in the early days was Ilmar Wilbers. He made extensive efforts with assisting the book project and establishing the university course INF1100. I feel that without Ilmar and his solutions to numerous technical problems the first edition of the book would never have been completed. Johannes H. Ring also deserves special acknowledgment for the development of the Easyviz graphics tool back in the days when Python plotting was a hassle, and later for his maintenance of software associated with the book.

Professor Loyce Adams studied the entire book, solved all the exercises, found numerous errors, and suggested many improvements. Her contributions are so much appreciated. More recently, Helmut Büch worked extremely carefully through all details in Chaps. 1–6, tested the software, found many typos, and asked critical questions that led to lots of significant improvements. I am so thankful for all his efforts and for his enthusiasm during the preparations of the fourth edition. The fifth edition has benefited much from Hakki Eres’ careful examination of the fourth edition. He found several typos and code errors, some of which go back to the first edition.

Special thanks go to Geir Kjetil Sandve for being the primary author of the computational bioinformatics examples in Sects. 3.3, 6.5, 8.3.4, and 9.5, with contributions from Sveinung Gundersen, Ksenia Khelik, Halfdan Rydbeck, and Kai Trengereid. I am also greatful to Øyvind Ryan’s work with linear algebra and visualization of scalar and vector fields in Chap. 5.

Several people have contributed with suggestions for improvements of the text, the exercises, and the associated software. I will in particular mention Ingrid Eide, Ståle Zerener Haugnæss, Kristian Hiorth, Timothy Keough, Arve Knudsen, Espen Kristensen, Tobias Vidarsson Langhoff, Martin Vonheim Larsen, Kine Veronica Lund, Solveig Masvie, Håkon Møller, Rebekka Mørken, Mathias Nedrebø, Marit Sandstad, Helene Norheim Semmerud, Lars Storjord, Fredrik Heffer Valdmanis, and Torkil Vederhus. Hakon Adler is greatly acknowledged for his careful reading of early various versions of the manuscript. Many thanks go to the professors Fred Espen Bent, Ørnulf Borgan, Geir Dahl, Knut Mørken, and Geir Pedersen for formulating several exciting exercises from various application fields. I also appreciate the cover image made by my good friend Jan Olav Langseth.

This book and the associated course are parts of a comprehensive and successful reform at the University of Oslo, called *Computing in Science Education*. The goal of the reform is to integrate computer programming and simulation in all bachelor courses in natural science where mathematical models are used. The present book lays the foundation for the modern computerized problem solving technique to be applied in later courses. It has been extremely inspiring to work closely with the driving forces behind this reform, especially the professors Morten Hjorth-Jensen, Anders Malthe-Sørensen, Knut Mørken, and Arnt Inge Vistnes.

The excellent assistance from the Springer system over the years, in particular Martin Peters, Thanh-Ha Le Thi, Ruth Allewelt, Peggy Glauch-Ruge, Nadja Kroke, Thomas Schmidt, Patrick Waltemate, Donatas Akmanavicius, and Yvonne Schlatter, is highly appreciated, and ensured a smooth and rapid production of all editions of this book.

Oslo, February 2016

Hans Petter Langtangen

---

# Contents

<b>1 Computing with Formulas . . . . .</b>	<b>1</b>
1.1 The First Programming Encounter: a Formula . . . . .	1
1.1.1 Using a Program as a Calculator . . . . .	2
1.1.2 About Programs and Programming . . . . .	2
1.1.3 Tools for Writing Programs . . . . .	3
1.1.4 Writing and Running Your First Python Program . . . . .	4
1.1.5 Warning About Typing Program Text . . . . .	5
1.1.6 Verifying the Result . . . . .	6
1.1.7 Using Variables . . . . .	6
1.1.8 Names of Variables . . . . .	6
1.1.9 Reserved Words in Python . . . . .	7
1.1.10 Comments . . . . .	8
1.1.11 Formatting Text and Numbers . . . . .	9
1.2 Computer Science Glossary . . . . .	12
1.3 Another Formula: Celsius-Fahrenheit Conversion . . . . .	16
1.3.1 Potential Error: Integer Division . . . . .	16
1.3.2 Objects in Python . . . . .	17
1.3.3 Avoiding Integer Division . . . . .	18
1.3.4 Arithmetic Operators and Precedence . . . . .	20
1.4 Evaluating Standard Mathematical Functions . . . . .	20
1.4.1 Example: Using the Square Root Function . . . . .	20
1.4.2 Example: Computing with $\sinh x$ . . . . .	23
1.4.3 A First Glimpse of Rounding Errors . . . . .	23
1.5 Interactive Computing . . . . .	24
1.5.1 Using the Python Shell . . . . .	25
1.5.2 Type Conversion . . . . .	26
1.5.3 IPython . . . . .	27
1.6 Complex Numbers . . . . .	29
1.6.1 Complex Arithmetics in Python . . . . .	30
1.6.2 Complex Functions in Python . . . . .	31
1.6.3 Unified Treatment of Complex and Real Functions . . . . .	31
1.7 Symbolic Computing . . . . .	33
1.7.1 Basic Differentiation and Integration . . . . .	33
1.7.2 Equation Solving . . . . .	34

1.7.3	Taylor Series and More . . . . .	35
1.8	Summary . . . . .	35
1.8.1	Chapter Topics . . . . .	35
1.8.2	Example: Trajectory of a Ball . . . . .	39
1.8.3	About Typesetting Conventions in This Book . . . . .	40
1.9	Exercises . . . . .	41
<b>2</b>	<b>Loops and Lists</b> . . . . .	51
2.1	While Loops . . . . .	51
2.1.1	A Naive Solution . . . . .	51
2.1.2	While Loops . . . . .	52
2.1.3	Boolean Expressions . . . . .	54
2.1.4	Loop Implementation of a Sum . . . . .	56
2.2	Lists . . . . .	57
2.2.1	Basic List Operations . . . . .	57
2.2.2	For Loops . . . . .	60
2.3	Alternative Implementations with Lists and Loops . . . . .	62
2.3.1	While Loop Implementation of a for Loop . . . . .	62
2.3.2	The Range Construction . . . . .	63
2.3.3	For Loops with List Indices . . . . .	64
2.3.4	Changing List Elements . . . . .	65
2.3.5	List Comprehension . . . . .	66
2.3.6	Traversing Multiple Lists Simultaneously . . . . .	66
2.4	Nested Lists . . . . .	67
2.4.1	A table as a List of Rows or Columns . . . . .	67
2.4.2	Printing Objects . . . . .	68
2.4.3	Extracting Sublists . . . . .	70
2.4.4	Traversing Nested Lists . . . . .	72
2.5	Tuples . . . . .	74
2.6	Summary . . . . .	75
2.6.1	Chapter Topics . . . . .	75
2.6.2	Example: Analyzing List Data . . . . .	78
2.6.3	How to Find More Python Information . . . . .	80
2.7	Exercises . . . . .	82
<b>3</b>	<b>Functions and Branching</b> . . . . .	91
3.1	Functions . . . . .	91
3.1.1	Mathematical Functions as Python Functions . . . . .	91
3.1.2	Understanding the Program Flow . . . . .	93
3.1.3	Local and Global Variables . . . . .	94
3.1.4	Multiple Arguments . . . . .	96
3.1.5	Function Argument or Global Variable? . . . . .	97
3.1.6	Beyond Mathematical Functions . . . . .	98
3.1.7	Multiple Return Values . . . . .	99
3.1.8	Computing Sums . . . . .	100
3.1.9	Functions with No Return Values . . . . .	101
3.1.10	Keyword Arguments . . . . .	103
3.1.11	Doc Strings . . . . .	105

---

3.1.12 Functions as Arguments to Functions . . . . .	107
3.1.13 The Main Program . . . . .	109
3.1.14 Lambda Functions . . . . .	110
3.2 Branching . . . . .	110
3.2.1 If-else Blocks . . . . .	111
3.2.2 Inline if Tests . . . . .	113
3.3 Mixing Loops, Branching, and Functions in Bioinformatics . . . . .	113
Examples . . . . .	113
3.3.1 Counting Letters in DNA Strings . . . . .	114
3.3.2 Efficiency Assessment . . . . .	118
3.3.3 Verifying the Implementations . . . . .	120
3.4 Summary . . . . .	121
3.4.1 Chapter Topics . . . . .	121
3.4.2 Example: Numerical Integration . . . . .	123
3.5 Exercises . . . . .	127
<b>4 User Input and Error Handling . . . . .</b>	<b>149</b>
4.1 Asking Questions and Reading Answers . . . . .	150
4.1.1 Reading Keyboard Input . . . . .	150
4.2 Reading from the Command Line . . . . .	151
4.2.1 Providing Input on the Command Line . . . . .	151
4.2.2 A Variable Number of Command-Line Arguments . . . . .	152
4.2.3 More on Command-Line Arguments . . . . .	153
4.3 Turning User Text into Live Objects . . . . .	154
4.3.1 The Magic Eval Function . . . . .	154
4.3.2 The Magic Exec Function . . . . .	158
4.3.3 Turning String Expressions into Functions . . . . .	160
4.4 Option-Value Pairs on the Command Line . . . . .	161
4.4.1 Basic Usage of the Argparse Module . . . . .	162
4.4.2 Mathematical Expressions as Values . . . . .	163
4.5 Reading Data from File . . . . .	165
4.5.1 Reading a File Line by Line . . . . .	166
4.5.2 Alternative Ways of Reading a File . . . . .	167
4.5.3 Reading a Mixture of Text and Numbers . . . . .	169
4.6 Writing Data to File . . . . .	171
4.6.1 Example: Writing a Table to File . . . . .	171
4.6.2 Standard Input and Output as File Objects . . . . .	173
4.6.3 What is a File, Really? . . . . .	176
4.7 Handling Errors . . . . .	179
4.7.1 Exception Handling . . . . .	180
4.7.2 Raising Exceptions . . . . .	183
4.8 A Glimpse of Graphical User Interfaces . . . . .	185
4.9 Making Modules . . . . .	188
4.9.1 Example: Interest on Bank Deposits . . . . .	188
4.9.2 Collecting Functions in a Module File . . . . .	189
4.9.3 Test Block . . . . .	190
4.9.4 Verification of the Module Code . . . . .	192
4.9.5 Getting Input Data . . . . .	193

4.9.6	Doc Strings in Modules . . . . .	195
4.9.7	Using Modules . . . . .	196
4.9.8	Distributing Modules . . . . .	199
4.9.9	Making Software Available on the Internet . . . . .	200
4.10	Making Code for Python 2 and 3 . . . . .	201
4.10.1	Basic Differences Between Python 2 and 3 . . . . .	201
4.10.2	Turning Python 2 Code into Python 3 Code . . . . .	202
4.11	Summary . . . . .	204
4.11.1	Chapter Topics . . . . .	204
4.11.2	Example: Bisection Root Finding . . . . .	208
4.12	Exercises . . . . .	216
<b>5</b>	<b>Array Computing and Curve Plotting . . . . .</b>	<b>227</b>
5.1	Vectors . . . . .	228
5.1.1	The Vector Concept . . . . .	228
5.1.2	Mathematical Operations on Vectors . . . . .	229
5.1.3	Vector Arithmetics and Vector Functions . . . . .	231
5.2	Arrays in Python Programs . . . . .	232
5.2.1	Using Lists for Collecting Function Data . . . . .	232
5.2.2	Basics of Numerical Python Arrays . . . . .	233
5.2.3	Computing Coordinates and Function Values . . . . .	235
5.2.4	Vectorization . . . . .	236
5.3	Curve Plotting . . . . .	238
5.3.1	MATLAB-Style Plotting with Matplotlib . . . . .	238
5.3.2	Matplotlib; Pyplot Prefix . . . . .	243
5.3.3	SciTools and Easyviz . . . . .	244
5.3.4	Making Animations . . . . .	249
5.3.5	Making Videos . . . . .	254
5.3.6	Curve Plots in Pure Text . . . . .	255
5.4	Plotting Difficulties . . . . .	256
5.4.1	Piecewisely Defined Functions . . . . .	256
5.4.2	Rapidly Varying Functions . . . . .	259
5.5	More Advanced Vectorization of Functions . . . . .	260
5.5.1	Vectorization of StringFunction Objects . . . . .	260
5.5.2	Vectorization of the Heaviside Function . . . . .	261
5.5.3	Vectorization of a Hat Function . . . . .	265
5.6	More on Numerical Python Arrays . . . . .	267
5.6.1	Copying Arrays . . . . .	267
5.6.2	In-Place Arithmetics . . . . .	268
5.6.3	Allocating Arrays . . . . .	269
5.6.4	Generalized Indexing . . . . .	269
5.6.5	Testing for the Array Type . . . . .	270
5.6.6	Compact Syntax for Array Generation . . . . .	271
5.6.7	Shape Manipulation . . . . .	271
5.7	High-Performance Computing with Arrays . . . . .	272
5.7.1	Scalar Implementation . . . . .	272
5.7.2	Vectorized Implementation . . . . .	273
5.7.3	Memory-Saving Implementation . . . . .	273

---

5.7.4	Analysis of Memory Usage . . . . .	275
5.7.5	Analysis of the CPU Time . . . . .	276
5.8	Higher-Dimensional Arrays . . . . .	277
5.8.1	Matrices and Arrays . . . . .	277
5.8.2	Two-Dimensional Numerical Python Arrays . . . . .	278
5.8.3	Array Computing . . . . .	281
5.8.4	Matrix Objects . . . . .	282
5.9	Some Common Linear Algebra Operations . . . . .	283
5.9.1	Inverse, Determinant, and Eigenvalues . . . . .	283
5.9.2	Products . . . . .	283
5.9.3	Norms . . . . .	284
5.9.4	Sum and Extreme Values . . . . .	284
5.9.5	Indexing . . . . .	286
5.9.6	Transpose and Upper/Lower Triangular Parts . . . . .	286
5.9.7	Solving Linear Systems . . . . .	287
5.9.8	Matrix Row and Column Operations . . . . .	287
5.9.9	Computing the Rank of a Matrix . . . . .	288
5.9.10	Symbolic Linear Algebra . . . . .	289
5.10	Plotting of Scalar and Vector Fields . . . . .	292
5.10.1	Installation . . . . .	292
5.10.2	Surface Plots . . . . .	293
5.10.3	Parameterized Curve . . . . .	293
5.10.4	Contour Lines . . . . .	294
5.10.5	The Gradient Vector Field . . . . .	294
5.11	Matplotlib . . . . .	296
5.11.1	Surface Plots . . . . .	296
5.11.2	Contour Plots . . . . .	297
5.11.3	Vector Field Plots . . . . .	299
5.12	Mayavi . . . . .	299
5.12.1	Surface Plots . . . . .	300
5.12.2	Contour Plots . . . . .	303
5.12.3	Vector Field Plots . . . . .	303
5.12.4	A 3D Scalar Field and Its Gradient Field . . . . .	304
5.12.5	Animations . . . . .	306
5.13	Summary . . . . .	307
5.13.1	Chapter Topics . . . . .	307
5.13.2	Example: Animating a Function . . . . .	308
5.14	Exercises . . . . .	313
6	<b>Dictionaries and Strings</b> . . . . .	333
6.1	Dictionaries . . . . .	333
6.1.1	Making Dictionaries . . . . .	334
6.1.2	Dictionary Operations . . . . .	334
6.1.3	Example: Polynomials as Dictionaries . . . . .	336
6.1.4	Dictionaries with Default Values and Ordering . . . . .	338
6.1.5	Example: Storing File Data in Dictionaries . . . . .	341
6.1.6	Example: Storing File Data in Nested Dictionaries . . . . .	342

6.1.7	Example: Reading and Plotting Data Recorded at Specific Dates . . . . .	347
6.2	Strings . . . . .	351
6.2.1	Common Operations on Strings . . . . .	351
6.2.2	Example: Reading Pairs of Numbers . . . . .	355
6.2.3	Example: Reading Coordinates . . . . .	358
6.3	Reading Data from Web Pages . . . . .	360
6.3.1	About Web Pages . . . . .	361
6.3.2	How to Access Web Pages in Programs . . . . .	362
6.3.3	Example: Reading Pure Text Files . . . . .	363
6.3.4	Example: Extracting Data from HTML . . . . .	365
6.3.5	Handling Non-English Text . . . . .	366
6.4	Reading and Writing Spreadsheet Files . . . . .	369
6.4.1	CSV Files . . . . .	369
6.4.2	Reading CSV Files . . . . .	370
6.4.3	Processing Spreadsheet Data . . . . .	371
6.4.4	Writing CSV Files . . . . .	372
6.4.5	Representing Number Cells with Numerical Python Arrays	373
6.4.6	Using More High-Level Numerical Python Functionality .	374
6.5	Examples from Analyzing DNA . . . . .	375
6.5.1	Computing Frequencies . . . . .	375
6.5.2	Analyzing the Frequency Matrix . . . . .	382
6.5.3	Finding Base Frequencies . . . . .	385
6.5.4	Translating Genes into Proteins . . . . .	388
6.5.5	Some Humans Can Drink Milk, While Others Cannot .	393
6.6	Making Code that is Compatible with Python 2 and 3 . . . . .	394
6.6.1	More Basic Differences Between Python 2 and 3 . . . . .	394
6.6.2	Turning Python 2 Code into Python 3 Code . . . . .	396
6.7	Summary . . . . .	396
6.7.1	Chapter Topics . . . . .	396
6.7.2	Example: A File Database . . . . .	398
6.8	Exercises . . . . .	402
<b>7</b>	<b>Introduction to Classes . . . . .</b>	<b>409</b>
7.1	Simple Function Classes . . . . .	409
7.1.1	Challenge: Functions with Parameters . . . . .	410
7.1.2	Representing a Function as a Class . . . . .	412
7.1.3	The Self Variable . . . . .	417
7.1.4	Another Function Class Example . . . . .	419
7.1.5	Alternative Function Class Implementations . . . . .	420
7.1.6	Making Classes Without the Class Construct . . . . .	422
7.1.7	Closures . . . . .	424
7.2	More Examples on Classes . . . . .	426
7.2.1	Bank Accounts . . . . .	426
7.2.2	Phone Book . . . . .	428
7.2.3	A Circle . . . . .	430
7.3	Special Methods . . . . .	432
7.3.1	The Call Special Method . . . . .	432

---

7.3.2	Example: Automagic Differentiation . . . . .	433
7.3.3	Example: Automagic Integration . . . . .	438
7.3.4	Turning an Instance into a String . . . . .	440
7.3.5	Example: Phone Book with Special Methods . . . . .	441
7.3.6	Adding Objects . . . . .	443
7.3.7	Example: Class for Polynomials . . . . .	443
7.3.8	Arithmetic Operations and Other Special Methods . . . . .	449
7.3.9	Special Methods for String Conversion . . . . .	449
7.4	Example: Class for Vectors in the Plane . . . . .	451
7.4.1	Some Mathematical Operations on Vectors . . . . .	451
7.4.2	Implementation . . . . .	452
7.4.3	Usage . . . . .	454
7.5	Example: Class for Complex Numbers . . . . .	455
7.5.1	Implementation . . . . .	455
7.5.2	Illegal Operations . . . . .	457
7.5.3	Mixing Complex and Real Numbers . . . . .	457
7.5.4	Dynamic, Static, Strong, Weak, and Duck Typing . . . . .	459
7.5.5	Special Methods for “Right” Operands . . . . .	460
7.5.6	Inspecting Instances . . . . .	461
7.6	Static Methods and Attributes . . . . .	463
7.7	Summary . . . . .	464
7.7.1	Chapter Topics . . . . .	464
7.7.2	Example: Interval Arithmetic . . . . .	466
7.8	Exercises . . . . .	470
<b>8</b>	<b>Random Numbers and Simple Games</b> . . . . .	489
8.1	Drawing Random Numbers . . . . .	489
8.1.1	The Seed . . . . .	490
8.1.2	Uniformly Distributed Random Numbers . . . . .	491
8.1.3	Visualizing the Distribution . . . . .	492
8.1.4	Vectorized Drawing of Random Numbers . . . . .	493
8.1.5	Computing the Mean and Standard Deviation . . . . .	494
8.1.6	The Gaussian or Normal Distribution . . . . .	496
8.2	Drawing Integers . . . . .	497
8.2.1	Random Integer Functions . . . . .	498
8.2.2	Example: Throwing a Die . . . . .	498
8.2.3	Drawing a Random Element from a List . . . . .	501
8.2.4	Example: Drawing Cards from a Deck . . . . .	502
8.2.5	Example: Class Implementation of a Deck . . . . .	504
8.3	Computing Probabilities . . . . .	507
8.3.1	Principles of Monte Carlo Simulation . . . . .	507
8.3.2	Example: Throwing Dice . . . . .	508
8.3.3	Example: Drawing Balls from a Hat . . . . .	511
8.3.4	Random Mutations of Genes . . . . .	513
8.3.5	Example: Policies for Limiting Population Growth . . . . .	519
8.4	Simple Games . . . . .	522
8.4.1	Guessing a Number . . . . .	522
8.4.2	Rolling Two Dice . . . . .	523

8.5	Monte Carlo Integration . . . . .	526
8.5.1	Derivation of Monte Carlo Integration . . . . .	526
8.5.2	Implementation of Standard Monte Carlo Integration . . . . .	528
8.5.3	Area Computing by Throwing Random Points . . . . .	531
8.6	Random Walk in One Space Dimension . . . . .	534
8.6.1	Basic Implementation . . . . .	534
8.6.2	Visualization . . . . .	535
8.6.3	Random Walk as a Difference Equation . . . . .	536
8.6.4	Computing Statistics of the Particle Positions . . . . .	536
8.6.5	Vectorized Implementation . . . . .	537
8.7	Random Walk in Two Space Dimensions . . . . .	539
8.7.1	Basic Implementation . . . . .	539
8.7.2	Vectorized Implementation . . . . .	541
8.8	Summary . . . . .	542
8.8.1	Chapter Topics . . . . .	542
8.8.2	Example: Random Growth . . . . .	544
8.9	Exercises . . . . .	549
<b>9</b>	<b>Object-Oriented Programming . . . . .</b>	<b>567</b>
9.1	Inheritance and Class Hierarchies . . . . .	567
9.1.1	A Class for Straight Lines . . . . .	568
9.1.2	A First Try on a Class for Parabolas . . . . .	569
9.1.3	A Class for Parabolas Using Inheritance . . . . .	569
9.1.4	Checking the Class Type . . . . .	571
9.1.5	Attribute vs Inheritance: has-a vs is-a Relationship . . . . .	572
9.1.6	Superclass for Defining an Interface . . . . .	574
9.2	Class Hierarchy for Numerical Differentiation . . . . .	576
9.2.1	Classes for Differentiation . . . . .	577
9.2.2	Verification . . . . .	579
9.2.3	A flexible Main Program . . . . .	581
9.2.4	Extensions . . . . .	582
9.2.5	Alternative Implementation via Functions . . . . .	585
9.2.6	Alternative Implementation via Functional Programming . . . . .	586
9.2.7	Alternative Implementation via a Single Class . . . . .	587
9.3	Class Hierarchy for Numerical Integration . . . . .	589
9.3.1	Numerical Integration Methods . . . . .	589
9.3.2	Classes for Integration . . . . .	590
9.3.3	Verification . . . . .	594
9.3.4	Using the Class Hierarchy . . . . .	595
9.3.5	About Object-Oriented Programming . . . . .	597
9.4	Class Hierarchy for Making Drawings . . . . .	599
9.4.1	Using the Object Collection . . . . .	600
9.4.2	Example of Classes for Geometric Objects . . . . .	609
9.4.3	Adding Functionality via Recursion . . . . .	614
9.4.4	Scaling, Translating, and Rotating a Figure . . . . .	618
9.5	Classes for DNA Analysis . . . . .	620
9.5.1	Class for Regions . . . . .	620
9.5.2	Class for Genes . . . . .	621

---

9.5.3 Subclasses . . . . .	626
9.6 Summary . . . . .	627
9.6.1 Chapter Topics . . . . .	627
9.6.2 Example: Input Data Reader . . . . .	629
9.7 Exercises . . . . .	635
<b>A Sequences and Difference Equations . . . . .</b>	<b>645</b>
A.1 Mathematical Models Based on Difference Equations . . . . .	646
A.1.1 Interest Rates . . . . .	647
A.1.2 The Factorial as a Difference Equation . . . . .	649
A.1.3 Fibonacci Numbers . . . . .	650
A.1.4 Growth of a Population . . . . .	651
A.1.5 Logistic Growth . . . . .	652
A.1.6 Payback of a Loan . . . . .	654
A.1.7 The Integral as a Difference Equation . . . . .	655
A.1.8 Taylor Series as a Difference Equation . . . . .	657
A.1.9 Making a Living from a Fortune . . . . .	658
A.1.10 Newton's Method . . . . .	659
A.1.11 The Inverse of a Function . . . . .	663
A.2 Programming with Sound . . . . .	665
A.2.1 Writing Sound to File . . . . .	666
A.2.2 Reading Sound from File . . . . .	667
A.2.3 Playing Many Notes . . . . .	667
A.2.4 Music of a Sequence . . . . .	668
A.3 Exercises . . . . .	671
<b>B Introduction to Discrete Calculus . . . . .</b>	<b>683</b>
B.1 Discrete Functions . . . . .	683
B.1.1 The Sine Function . . . . .	684
B.1.2 Interpolation . . . . .	685
B.1.3 Evaluating the Approximation . . . . .	686
B.1.4 Generalization . . . . .	687
B.2 Differentiation Becomes Finite Differences . . . . .	688
B.2.1 Differentiating the Sine Function . . . . .	689
B.2.2 Differences on a Mesh . . . . .	690
B.2.3 Generalization . . . . .	692
B.3 Integration Becomes Summation . . . . .	693
B.3.1 Dividing into Subintervals . . . . .	693
B.3.2 Integration on Subintervals . . . . .	695
B.3.3 Adding the Subintervals . . . . .	696
B.3.4 Generalization . . . . .	697
B.4 Taylor Series . . . . .	699
B.4.1 Approximating Functions Close to One Point . . . . .	699
B.4.2 Approximating the Exponential Function . . . . .	699
B.4.3 More Accurate Expansions . . . . .	700
B.4.4 Accuracy of the Approximation . . . . .	702
B.4.5 Derivatives Revisited . . . . .	704
B.4.6 More Accurate Difference Approximations . . . . .	705

B.4.7	Second-Order Derivatives . . . . .	707
B.5	Exercises . . . . .	709
C	<b>Introduction to differential equations</b> . . . . .	715
C.1	The simplest case . . . . .	716
C.2	Exponential Growth . . . . .	718
C.3	Logistic Growth . . . . .	723
C.4	A Simple Pendulum . . . . .	724
C.5	A Model for the Spreading of a Disease . . . . .	727
C.6	Exercises . . . . .	729
D	<b>A Complete Differential Equation Project</b> . . . . .	731
D.1	About the Problem: Motion and Forces in Physics . . . . .	731
D.1.1	The Physical Problem . . . . .	731
D.1.2	The Computational Algorithm . . . . .	733
D.1.3	Derivation of the Mathematical Model . . . . .	734
D.1.4	Derivation of the Algorithm . . . . .	736
D.2	Program Development and Testing . . . . .	737
D.2.1	Implementation . . . . .	737
D.2.2	Callback Functionality . . . . .	740
D.2.3	Making a Module . . . . .	742
D.2.4	Verification . . . . .	743
D.3	Visualization . . . . .	746
D.3.1	Simultaneous Computation and Plotting . . . . .	746
D.3.2	Some Applications . . . . .	748
D.3.3	Remark on Choosing $\Delta t$ . . . . .	749
D.3.4	Comparing Several Quantities in Subplots . . . . .	750
D.3.5	Comparing Approximate and Exact Solutions . . . . .	751
D.3.6	Evolution of the Error as $\Delta t$ Decreases . . . . .	752
D.4	Exercises . . . . .	755
E	<b>Programming of Differential Equations</b> . . . . .	757
E.1	Scalar Ordinary Differential Equations . . . . .	758
E.1.1	Examples on Right-Hand-Side Functions . . . . .	758
E.1.2	The Forward Euler Scheme . . . . .	759
E.1.3	Function Implementation . . . . .	760
E.1.4	Verifying the Implementation . . . . .	761
E.1.5	From Discrete to Continuous Solution . . . . .	763
E.1.6	Switching Numerical Method . . . . .	764
E.1.7	Class Implementation . . . . .	764
E.1.8	Logistic Growth via a Function-Based Approach . . . . .	769
E.1.9	Logistic Growth via a Class-Based Approach . . . . .	769
E.2	Systems of Ordinary Differential Equations . . . . .	772
E.2.1	Mathematical Problem . . . . .	773
E.2.2	Example of a System of ODEs . . . . .	774
E.2.3	Function Implementation . . . . .	775
E.2.4	Class Implementation . . . . .	777
E.3	The ODESolver Class Hierarchy . . . . .	779

---

E.3.1	Numerical Methods . . . . .	779
E.3.2	Construction of a Solver Hierarchy . . . . .	780
E.3.3	The Backward Euler Method . . . . .	783
E.3.4	Verification . . . . .	785
E.3.5	Example: Exponential Decay . . . . .	787
E.3.6	Example: The Logistic Equation with Problem and Solver Classes . . . . .	789
E.3.7	Example: An Oscillating System . . . . .	797
E.3.8	Application 4: The Trajectory of a Ball . . . . .	799
E.3.9	Further Developments of ODESolver . . . . .	801
E.4	Exercises . . . . .	802
<b>F</b>	<b>Debugging . . . . .</b>	<b>835</b>
F.1	Using a Debugger . . . . .	835
F.2	How to Debug . . . . .	838
F.2.1	A Recipe for Program Writing and Debugging . . . . .	838
F.2.2	Application of the Recipe . . . . .	841
F.2.3	Getting Help from a Code Analyzer . . . . .	853
<b>G</b>	<b>Migrating Python to Compiled Code . . . . .</b>	<b>857</b>
G.1	Pure Python Code for Monte Carlo Simulation . . . . .	857
G.1.1	The Computational Problem . . . . .	858
G.1.2	A Scalar Python Implementation . . . . .	858
G.1.3	A Vectorized Python Implementation . . . . .	859
G.2	Migrating Scalar Python Code to Cython . . . . .	860
G.2.1	A Plain Cython Implementation . . . . .	860
G.2.2	A Better Cython Implementation . . . . .	863
G.3	Migrating Code to C . . . . .	865
G.3.1	Writing a C Program . . . . .	865
G.3.2	Migrating Loops to C Code via F2PY . . . . .	866
G.3.3	Migrating Loops to C Code via Cython . . . . .	867
G.3.4	Comparing Efficiency . . . . .	868
<b>H</b>	<b>Technical Topics . . . . .</b>	<b>871</b>
H.1	Getting Access to Python . . . . .	871
H.1.1	Required Software . . . . .	871
H.1.2	Installing Software on Your Laptop: Mac OS X and Windows . . . . .	872
H.1.3	Anaconda and Spyder . . . . .	873
H.1.4	VMWare Fusion Virtual Machine . . . . .	874
H.1.5	Dual Boot on Windows . . . . .	877
H.1.6	Vagrant Virtual Machine . . . . .	877
H.2	How to Write and Run a Python Program . . . . .	878
H.2.1	The Need for a Text Editor . . . . .	878
H.2.2	Terminal Windows . . . . .	880
H.3	The SageMathCloud and Wakari Web Services . . . . .	880
H.3.1	Basic Intro to SageMathCloud . . . . .	880
H.3.2	Basic Intro to Wakari . . . . .	881

H.3.3	Installing Your Own Python Packages . . . . .	881
H.4	Writing IPython Notebooks . . . . .	882
H.4.1	A Simple Program in the Notebook . . . . .	882
H.4.2	Mixing Text, Mathematics, Code, and Graphics . . . . .	882
H.5	Different Ways of Running Python Programs . . . . .	884
H.5.1	Executing Python Programs in iPython . . . . .	884
H.5.2	Executing Python Programs in Unix . . . . .	884
H.5.3	Executing Python Programs in Windows . . . . .	885
H.5.4	Executing Python Programs in Mac OS X . . . . .	887
H.5.5	Making a Complete Stand-Alone Executable . . . . .	887
H.6	Doing Operating System Tasks in Python . . . . .	888
H.7	Variable Number of Function Arguments . . . . .	891
H.7.1	Variable Number of Positional Arguments . . . . .	891
H.7.2	Variable Number of Keyword Arguments . . . . .	894
H.8	Evaluating Program Efficiency . . . . .	896
H.8.1	Making Time Measurements . . . . .	896
H.8.2	Profiling Python Programs . . . . .	898
H.9	Software Testing . . . . .	899
H.9.1	Requirements of the Test Function . . . . .	900
H.9.2	Writing the Test Function; Precomputed Data . . . . .	900
H.9.3	Writing the Test Function; Exact Numerical Solution . . . . .	901
H.9.4	Testing of Function Robustness . . . . .	902
H.9.5	Automatic Execution of Tests . . . . .	904
<b>References</b>	.....	907
<b>Index</b>	.....	909

---

## List of Exercises

Exercise 1.1: Compute 1+1 . . . . .	42
Exercise 1.2: Write a Hello World program . . . . .	43
Exercise 1.3: Derive and compute a formula . . . . .	43
Exercise 1.4: Convert from meters to British length units . . . . .	43
Exercise 1.5: Compute the mass of various substances . . . . .	43
Exercise 1.6: Compute the growth of money in a bank . . . . .	43
Exercise 1.7: Find error(s) in a program . . . . .	43
Exercise 1.8: Type in program text . . . . .	43
Exercise 1.9: Type in programs and debug them . . . . .	44
Exercise 1.10: Evaluate a Gaussian function . . . . .	45
Exercise 1.11: Compute the air resistance on a football . . . . .	45
Exercise 1.12: How to cook the perfect egg . . . . .	46
Exercise 1.13: Derive the trajectory of a ball . . . . .	46
Exercise 1.14: Find errors in the coding of formulas . . . . .	47
Exercise 1.15: Explain why a program does not work . . . . .	47
Exercise 1.16: Find errors in Python statements . . . . .	48
Exercise 1.17: Find errors in the coding of a formula . . . . .	48
Exercise 1.18: Find errors in a program . . . . .	49
Exercise 2.1: Make a Fahrenheit-Celsius conversion table . . . . .	82
Exercise 2.2: Generate an approximate Fahrenheit-Celsius conversion table . . . . .	82
Exercise 2.3: Work with a list . . . . .	82
Exercise 2.4: Generate odd numbers . . . . .	82
Exercise 2.5: Compute the sum of the first $n$ integers . . . . .	82
Exercise 2.6: Compute energy levels in an atom . . . . .	82
Exercise 2.7: Generate equally spaced coordinates . . . . .	83
Exercise 2.8: Make a table of values from a formula . . . . .	83
Exercise 2.9: Store values from a formula in lists . . . . .	83
Exercise 2.10: Simulate operations on lists by hand . . . . .	84
Exercise 2.11: Compute a mathematical sum . . . . .	84
Exercise 2.12: Replace a while loop by a for loop . . . . .	84
Exercise 2.13: Simulate a program by hand . . . . .	85
Exercise 2.14: Explore Python documentation . . . . .	85
Exercise 2.15: Index a nested list . . . . .	85
Exercise 2.16: Store data in lists . . . . .	86

Exercise 2.17: Store data in a nested list . . . . .	86
Exercise 2.18: Values of boolean expressions . . . . .	86
Exercise 2.19: Explore round-off errors from a large number of inverse operations . . . . .	87
Exercise 2.20: Explore what zero can be on a computer . . . . .	87
Exercise 2.21: Compare two real numbers with a tolerance . . . . .	87
Exercise 2.22: Interpret a code . . . . .	88
Exercise 2.23: Explore problems with inaccurate indentation . . . . .	88
Exercise 2.24: Explore punctuation in Python programs . . . . .	89
Exercise 2.25: Investigate a for loop over a changing list . . . . .	89
Exercise 3.1: Implement a simple mathematical function . . . . .	127
Exercise 3.2: Implement a simple mathematical function with a parameter . . . . .	127
Exercise 3.3: Explain how a program works . . . . .	128
Exercise 3.4: Write a Fahrenheit-Celsius conversion functions . . . . .	128
Exercise 3.5: Write a test function for Exercise 3.4 . . . . .	128
Exercise 3.6: Given a test function, write the function . . . . .	128
Exercise 3.7: Evaluate a sum and write a test function . . . . .	129
Exercise 3.8: Write a function for solving $ax^2 + bx + c = 0$ . . . . .	129
Exercise 3.9: Implement the sum function . . . . .	129
Exercise 3.10: Compute a polynomial via a product . . . . .	130
Exercise 3.11: Integrate a function by the Trapezoidal rule . . . . .	130
Exercise 3.12: Derive the general Midpoint integration rule . . . . .	131
Exercise 3.13: Make an adaptive Trapezoidal rule . . . . .	132
Exercise 3.14: Simulate a program by hand . . . . .	133
Exercise 3.15: Debug a given test function . . . . .	134
Exercise 3.16: Compute the area of an arbitrary triangle . . . . .	134
Exercise 3.17: Compute the length of a path . . . . .	135
Exercise 3.18: Approximate $\pi$ . . . . .	135
Exercise 3.19: Compute the area of a polygon . . . . .	135
Exercise 3.20: Write functions . . . . .	136
Exercise 3.21: Approximate a function by a sum of sines . . . . .	136
Exercise 3.22: Implement a Gaussian function . . . . .	137
Exercise 3.23: Wrap a formula in a function . . . . .	137
Exercise 3.24: Write a function for numerical differentiation . . . . .	137
Exercise 3.25: Implement the factorial function . . . . .	137
Exercise 3.26: Compute velocity and acceleration from 1D position data . . . . .	138
Exercise 3.27: Find the max and min values of a function . . . . .	138
Exercise 3.28: Find the max and min elements in a list . . . . .	139
Exercise 3.29: Implement the Heaviside function . . . . .	139
Exercise 3.30: Implement a smoothed Heaviside function . . . . .	139
Exercise 3.31: Implement an indicator function . . . . .	140
Exercise 3.32: Implement a piecewise constant function . . . . .	140
Exercise 3.33: Apply indicator functions . . . . .	141
Exercise 3.34: Test your understanding of branching . . . . .	141
Exercise 3.35: Simulate nested loops by hand . . . . .	141
Exercise 3.36: Rewrite a mathematical function . . . . .	142
Exercise 3.37: Make a table for approximations of $\cos x$ . . . . .	142
Exercise 3.38: Use None in keyword arguments . . . . .	143

---

Exercise 3.39: Write a sort function for a list of 4-tuples . . . . .	143
Exercise 3.40: Find prime numbers . . . . .	145
Exercise 3.41: Find pairs of characters . . . . .	145
Exercise 3.42: Count substrings . . . . .	145
Exercise 3.43: Resolve a problem with a function . . . . .	145
Exercise 3.44: Determine the types of some objects . . . . .	146
Exercise 3.45: Find an error in a program . . . . .	146
Exercise 4.1: Make an interactive program . . . . .	216
Exercise 4.2: Read a number from the command line . . . . .	216
Exercise 4.3: Read a number from a file . . . . .	216
Exercise 4.4: Read and write several numbers from and to file . . . . .	217
Exercise 4.5: Use exceptions to handle wrong input . . . . .	217
Exercise 4.6: Read input from the keyboard . . . . .	217
Exercise 4.7: Read input from the command line . . . . .	217
Exercise 4.8: Try MSWord or LibreOffice to write a program . . . . .	218
Exercise 4.9: Prompt the user for input to a formula . . . . .	218
Exercise 4.10: Read parameters in a formula from the command line . . . . .	218
Exercise 4.11: Use exceptions to handle wrong input . . . . .	218
Exercise 4.12: Test validity of input data . . . . .	219
Exercise 4.13: Raise an exception in case of wrong input . . . . .	219
Exercise 4.14: Evaluate a formula for data in a file . . . . .	219
Exercise 4.15: Write a function given its test function . . . . .	219
Exercise 4.16: Compute the distance it takes to stop a car . . . . .	220
Exercise 4.17: Look up calendar functionality . . . . .	221
Exercise 4.18: Use the StringFunction tool . . . . .	221
Exercise 4.19: Why we test for specific exception types . . . . .	221
Exercise 4.20: Make a complete module . . . . .	221
Exercise 4.21: Organize a previous program as a module . . . . .	222
Exercise 4.22: Read options and values from the command line . . . . .	222
Exercise 4.23: Check if mathematical identities hold . . . . .	222
Exercise 4.24: Compute probabilities with the binomial distribution . . . . .	224
Exercise 4.25: Compute probabilities with the Poisson distribution . . . . .	224
Exercise 5.1: Fill lists with function values . . . . .	313
Exercise 5.2: Fill arrays; loop version . . . . .	313
Exercise 5.3: Fill arrays; vectorized version . . . . .	313
Exercise 5.4: Plot a function . . . . .	313
Exercise 5.5: Apply a function to a vector . . . . .	313
Exercise 5.6: Simulate by hand a vectorized expression . . . . .	313
Exercise 5.7: Demonstrate array slicing . . . . .	314
Exercise 5.8: Replace list operations by array computing . . . . .	314
Exercise 5.9: Plot a formula . . . . .	314
Exercise 5.10: Plot a formula for several parameters . . . . .	314
Exercise 5.11: Specify the extent of the axes in a plot . . . . .	314
Exercise 5.12: Plot exact and inexact Fahrenheit-Celsius conversion formulas	314
Exercise 5.13: Plot the trajectory of a ball . . . . .	314
Exercise 5.14: Plot data in a two-column file . . . . .	315
Exercise 5.15: Write function data to file . . . . .	315
Exercise 5.16: Plot data from a file . . . . .	316

Exercise 5.17: Write table to file . . . . .	316
Exercise 5.18: Fit a polynomial to data points . . . . .	317
Exercise 5.19: Fit a polynomial to experimental data . . . . .	318
Exercise 5.20: Read acceleration data and find velocities . . . . .	318
Exercise 5.21: Read acceleration data and plot velocities . . . . .	319
Exercise 5.22: Plot a trip's path and velocity from GPS coordinates . . . . .	319
Exercise 5.23: Vectorize the Midpoint rule for integration . . . . .	320
Exercise 5.24: Vectorize a function for computing the area of a polygon . . . . .	320
Exercise 5.25: Implement Lagrange's interpolation formula . . . . .	321
Exercise 5.26: Plot Lagrange's interpolating polynomial . . . . .	321
Exercise 5.27: Investigate the behavior of Lagrange's interpolating polynomials	322
Exercise 5.28: Plot a wave packet . . . . .	322
Exercise 5.29: Judge a plot . . . . .	322
Exercise 5.30: Plot the viscosity of water . . . . .	323
Exercise 5.31: Explore a complicated function graphically . . . . .	323
Exercise 5.32: Plot Taylor polynomial approximations to $\sin x$ . . . . .	323
Exercise 5.33: Animate a wave packet . . . . .	324
Exercise 5.34: Animate a smoothed Heaviside function . . . . .	324
Exercise 5.35: Animate two-scale temperature variations . . . . .	324
Exercise 5.36: Use non-uniformly distributed coordinates for visualization .	325
Exercise 5.37: Animate a sequence of approximations to $\pi$ . . . . .	325
Exercise 5.38: Animate a planet's orbit . . . . .	325
Exercise 5.39: Animate the evolution of Taylor polynomials . . . . .	326
Exercise 5.40: Plot the velocity profile for pipeflow . . . . .	327
Exercise 5.41: Plot sum-of-sines approximations to a function . . . . .	327
Exercise 5.42: Animate the evolution of a sum-of-sine approximation to a function . . . . .	327
Exercise 5.43: Plot functions from the command line . . . . .	328
Exercise 5.44: Improve command-line input . . . . .	328
Exercise 5.45: Demonstrate energy concepts from physics . . . . .	328
Exercise 5.46: Plot a w-like function . . . . .	328
Exercise 5.47: Plot a piecewise constant function . . . . .	329
Exercise 5.48: Vectorize a piecewise constant function . . . . .	329
Exercise 5.49: Visualize approximations in the Midpoint integration rule .	329
Exercise 5.50: Visualize approximations in the Trapezoidal integration rule	330
Exercise 5.51: Experience overflow in a function . . . . .	330
Exercise 5.52: Apply a function to a rank 2 array . . . . .	331
Exercise 5.53: Explain why array computations fail . . . . .	331
Exercise 5.54: Verify linear algebra results . . . . .	331
Exercise 6.1: Make a dictionary from a table . . . . .	402
Exercise 6.2: Explore syntax differences: lists vs. dicts . . . . .	402
Exercise 6.3: Use string operations to improve a program . . . . .	403
Exercise 6.4: Interpret output from a program . . . . .	403
Exercise 6.5: Make a dictionary . . . . .	403
Exercise 6.6: Make a nested dictionary . . . . .	404
Exercise 6.7: Make a nested dictionary from a file . . . . .	404
Exercise 6.8: Make a nested dictionary from a file . . . . .	404
Exercise 6.9: Compute the area of a triangle . . . . .	405

---

Exercise 6.10: Compare data structures for polynomials . . . . .	405
Exercise 6.11: Compute the derivative of a polynomial . . . . .	405
Exercise 6.12: Specify functions on the command line . . . . .	405
Exercise 6.13: Interpret function specifications . . . . .	406
Exercise 6.14: Compare average temperatures in cities . . . . .	407
Exercise 6.15: Generate an HTML report with figures . . . . .	407
Exercise 6.16: Allow different types for a function argument . . . . .	408
Exercise 6.17: Make a function more robust . . . . .	408
Exercise 6.18: Find proportion of bases inside/outside exons . . . . .	408
Exercise 7.1: Make a function class . . . . .	470
Exercise 7.2: Add a data attribute to a class . . . . .	471
Exercise 7.3: Add functionality to a class . . . . .	471
Exercise 7.4: Make classes for a rectangle and a triangle . . . . .	471
Exercise 7.5: Make a class for quadratic functions . . . . .	472
Exercise 7.6: Make a class for straight lines . . . . .	472
Exercise 7.7: Flexible handling of function arguments . . . . .	472
Exercise 7.8: Wrap functions in a class . . . . .	473
Exercise 7.9: Flexible handling of function arguments . . . . .	473
Exercise 7.10: Deduce a class implementation . . . . .	474
Exercise 7.11: Implement special methods in a class . . . . .	474
Exercise 7.12: Make a class for summation of series . . . . .	474
Exercise 7.13: Apply a numerical differentiation class . . . . .	475
Exercise 7.14: Implement an addition operator . . . . .	475
Exercise 7.15: Implement in-place <code>+=</code> and <code>-=</code> operators . . . . .	476
Exercise 7.16: Implement a class for numerical differentiation . . . . .	476
Exercise 7.17: Examine a program . . . . .	477
Exercise 7.18: Modify a class for numerical differentiation . . . . .	477
Exercise 7.19: Make a class for the Heaviside function . . . . .	478
Exercise 7.20: Make a class for the indicator function . . . . .	478
Exercise 7.21: Make a class for piecewise constant functions . . . . .	479
Exercise 7.22: Speed up repeated integral calculations . . . . .	479
Exercise 7.23: Apply a class for polynomials . . . . .	480
Exercise 7.24: Find a bug in a class for polynomials . . . . .	480
Exercise 7.25: Implement subtraction of polynomials . . . . .	480
Exercise 7.26: Test the functionality of pretty print of polynomials . . . . .	480
Exercise 7.27: Vectorize a class for polynomials . . . . .	481
Exercise 7.28: Use a dict to hold polynomial coefficients . . . . .	481
Exercise 7.29: Extend class Vec2D to work with lists/tuples . . . . .	482
Exercise 7.30: Extend class Vec2D to 3D vectors . . . . .	483
Exercise 7.31: Use NumPy arrays in class Vec2D . . . . .	483
Exercise 7.32: Impreciseness of interval arithmetics . . . . .	484
Exercise 7.33: Make classes for students and courses . . . . .	484
Exercise 7.34: Find local and global extrema of a function . . . . .	484
Exercise 7.35: Find the optimal production for a company . . . . .	485
Exercise 8.1: Flip a coin times . . . . .	549
Exercise 8.2: Compute a probability . . . . .	550
Exercise 8.3: Choose random colors . . . . .	550
Exercise 8.4: Draw balls from a hat . . . . .	550

Exercise 8.5: Computing probabilities of rolling dice . . . . .	550
Exercise 8.6: Estimate the probability in a dice game . . . . .	550
Exercise 8.7: Compute the probability of hands of cards . . . . .	551
Exercise 8.8: Decide if a dice game is fair . . . . .	551
Exercise 8.9: Adjust a game to make it fair . . . . .	551
Exercise 8.10: Make a test function for Monte Carlo simulation . . . . .	551
Exercise 8.11: Generalize a game . . . . .	551
Exercise 8.12: Compare two playing strategies . . . . .	552
Exercise 8.13: Investigate strategies in a game . . . . .	552
Exercise 8.14: Investigate the winning chances of some games . . . . .	552
Exercise 8.15: Compute probabilities of throwing two dice . . . . .	553
Exercise 8.16: Vectorize flipping a coin . . . . .	553
Exercise 8.17: Vectorize a probability computation . . . . .	553
Exercise 8.18: Throw dice and compute a small probability . . . . .	553
Exercise 8.19: Is democracy reliable as a decision maker? . . . . .	553
Exercise 8.20: Difference equation for random numbers . . . . .	555
Exercise 8.21: Make a class for drawing balls from a hat . . . . .	555
Exercise 8.22: Independent versus dependent random numbers . . . . .	555
Exercise 8.23: Compute the probability of flipping a coin . . . . .	556
Exercise 8.24: Simulate binomial experiments . . . . .	557
Exercise 8.25: Simulate a poker game . . . . .	557
Exercise 8.26: Estimate growth in a simulation model . . . . .	557
Exercise 8.27: Investigate guessing strategies . . . . .	557
Exercise 8.28: Vectorize a dice game . . . . .	558
Exercise 8.29: Compute $\pi$ by a Monte Carlo method . . . . .	558
Exercise 8.30: Compute $\pi$ by a Monte Carlo method . . . . .	558
Exercise 8.31: Compute $\pi$ by a random sum . . . . .	558
Exercise 8.32: 1D random walk with drift . . . . .	558
Exercise 8.33: 1D random walk until a point is hit . . . . .	558
Exercise 8.34: Simulate making a fortune from gaming . . . . .	559
Exercise 8.35: Simulate pollen movements as a 2D random walk . . . . .	559
Exercise 8.36: Make classes for 2D random walk . . . . .	559
Exercise 8.37: 2D random walk with walls; scalar version . . . . .	560
Exercise 8.38: 2D random walk with walls; vectorized version . . . . .	560
Exercise 8.39: Simulate mixing of gas molecules . . . . .	561
Exercise 8.40: Simulate slow mixing of gas molecules . . . . .	561
Exercise 8.41: Guess beer brands . . . . .	561
Exercise 8.42: Simulate stock prices . . . . .	562
Exercise 8.43: Compute with option prices in finance . . . . .	562
Exercise 8.44: Differentiate noise measurements . . . . .	563
Exercise 8.45: Differentiate noisy signals . . . . .	564
Exercise 8.46: Model noise in a time signal . . . . .	565
Exercise 8.47: Speed up Markov chain mutation . . . . .	566
Exercise 9.1: Demonstrate the magic of inheritance . . . . .	635
Exercise 9.2: Make polynomial subclasses of parabolas . . . . .	635
Exercise 9.3: Implement a class for a function as a subclass . . . . .	636
Exercise 9.4: Create an alternative class hierarchy for polynomials . . . . .	636
Exercise 9.5: Make circle a subclass of an ellipse . . . . .	636

---

Exercise 9.6: Make super- and subclass for a point . . . . .	636
Exercise 9.7: Modify a function class by subclassing . . . . .	637
Exercise 9.8: Explore the accuracy of difference formulas . . . . .	637
Exercise 9.9: Implement a subclass . . . . .	637
Exercise 9.10: Make classes for numerical differentiation . . . . .	638
Exercise 9.11: Implement a new subclass for differentiation . . . . .	638
Exercise 9.12: Understand if a class can be used recursively . . . . .	638
Exercise 9.13: Represent people by a class hierarchy . . . . .	638
Exercise 9.14: Add a new class in a class hierarchy . . . . .	639
Exercise 9.15: Compute convergence rates of numerical integration methods .	640
Exercise 9.16: Add common functionality in a class hierarchy . . . . .	641
Exercise 9.17: Make a class hierarchy for root finding . . . . .	641
Exercise 9.18: Make a calculus calculator class . . . . .	641
Exercise 9.19: Compute inverse functions . . . . .	642
Exercise 9.20: Make line drawing of a person; program . . . . .	643
Exercise 9.21: Make line drawing of a person; class . . . . .	643
Exercise 9.22: Animate a person with waving hands . . . . .	643
Exercise A.1: Determine the limit of a sequence . . . . .	671
Exercise A.2: Compute $\pi$ via sequences . . . . .	672
Exercise A.3: Reduce memory usage of difference equations . . . . .	672
Exercise A.4: Compute the development of a loan . . . . .	672
Exercise A.5: Solve a system of difference equations . . . . .	672
Exercise A.6: Modify a model for fortune development . . . . .	672
Exercise A.7: Change index in a difference equation . . . . .	673
Exercise A.8: Construct time points from dates . . . . .	673
Exercise A.9: Visualize the convergence of Newton's method . . . . .	674
Exercise A.10: Implement the secant method . . . . .	674
Exercise A.11: Test different methods for root finding . . . . .	675
Exercise A.12: Make difference equations for the Midpoint rule . . . . .	675
Exercise A.13: Compute the arc length of a curve . . . . .	675
Exercise A.14: Find difference equations for computing $\sin x$ . . . . .	676
Exercise A.15: Find difference equations for computing $\cos x$ . . . . .	677
Exercise A.16: Make a guitar-like sound . . . . .	677
Exercise A.17: Damp the bass in a sound file . . . . .	677
Exercise A.18: Damp the treble in a sound file . . . . .	678
Exercise A.19: Demonstrate oscillatory solutions of the logistic equation .	678
Exercise A.20: Automate computer experiments . . . . .	679
Exercise A.21: Generate an HTML report . . . . .	679
Exercise A.22: Use a class to archive and report experiments . . . . .	680
Exercise A.23: Explore logistic growth interactively . . . . .	681
Exercise A.24: Simulate the price of wheat . . . . .	681
Exercise B.1: Interpolate a discrete function . . . . .	709
Exercise B.2: Study a function for different parameter values . . . . .	710
Exercise B.3: Study a function and its derivative . . . . .	710
Exercise B.4: Use the Trapezoidal method . . . . .	711
Exercise B.5: Compute a sequence of integrals . . . . .	711
Exercise B.6: Use the Trapezoidal method . . . . .	712
Exercise B.7: Compute trigonometric integrals . . . . .	712

Exercise B.8: Plot functions and their derivatives . . . . .	713
Exercise B.9: Use the Trapezoidal method . . . . .	714
Exercise C.1: Solve a nonhomogeneous linear ODE . . . . .	729
Exercise C.2: Solve a nonlinear ODE . . . . .	729
Exercise C.3: Solve an ODE for $y(x)$ . . . . .	729
Exercise C.4: Experience instability of an ODE . . . . .	730
Exercise C.5: Solve an ODE with time-varying growth . . . . .	730
Exercise D.1: Model sudden movements of the plate . . . . .	755
Exercise D.2: Write a callback function . . . . .	756
Exercise D.3: Improve input to the simulation program . . . . .	756
Exercise E.1: Solve a simple ODE with function-based code . . . . .	802
Exercise E.2: Solve a simple ODE with class-based code . . . . .	802
Exercise E.3: Solve a simple ODE with the ODESolver hierarchy . . . . .	802
Exercise E.4: Solve an ODE specified on the command line . . . . .	802
Exercise E.5: Implement a numerical method for ODEs . . . . .	803
Exercise E.6: Solve an ODE for emptying a tank . . . . .	803
Exercise E.7: Solve an ODE for the arc length . . . . .	804
Exercise E.8: Simulate a falling or rising body in a fluid . . . . .	804
Exercise E.9: Verify the limit of a solution as time grows . . . . .	805
Exercise E.10: Scale the logistic equation . . . . .	806
Exercise E.11: Compute logistic growth with time-varying carrying capacity . . . . .	806
Exercise E.12: Solve an ODE until constant solution . . . . .	807
Exercise E.13: Use a problem class to hold data about an ODE . . . . .	807
Exercise E.14: Derive and solve a scaled ODE problem . . . . .	808
Exercise E.15: Clean up a file to make it a module . . . . .	809
Exercise E.16: Simulate radioactive decay . . . . .	809
Exercise E.17: Compute inverse functions by solving an ODE . . . . .	809
Exercise E.18: Make a class for computing inverse functions . . . . .	810
Exercise E.19: Add functionality to a class . . . . .	810
Exercise E.20: Compute inverse functions by interpolation . . . . .	811
Exercise E.21: Code the 4th-order Runge-Kutta method; function . . . . .	811
Exercise E.22: Code the 4th-order Runge-Kutta method; class . . . . .	811
Exercise E.23: Compare ODE methods . . . . .	811
Exercise E.24: Code a test function for systems of ODEs . . . . .	812
Exercise E.25: Code Heun's method for ODE systems; function . . . . .	812
Exercise E.26: Code Heun's method for ODE systems; class . . . . .	812
Exercise E.27: Implement and test the Leapfrog method . . . . .	812
Exercise E.28: Implement and test an Adams-Bashforth method . . . . .	813
Exercise E.29: Solve two coupled ODEs for radioactive decay . . . . .	813
Exercise E.30: Implement a 2nd-order Runge-Kutta method; function . . . . .	813
Exercise E.31: Implement a 2nd-order Runge-Kutta method; class . . . . .	813
Exercise E.32: Code the iterated midpoint method; function . . . . .	814
Exercise E.33: Code the iterated midpoint method; class . . . . .	814
Exercise E.34: Make a subclass for the iterated midpoint method . . . . .	815
Exercise E.35: Compare the accuracy of various methods for ODEs . . . . .	815
Exercise E.36: Animate how various methods for ODEs converge . . . . .	815
Exercise E.37: Study convergence of numerical methods for ODEs . . . . .	815
Exercise E.38: Find a body's position along with its velocity . . . . .	816

Exercise E.39: Add the effect of air resistance on a ball . . . . .	816
Exercise E.40: Solve an ODE system for an electric circuit . . . . .	817
Exercise E.41: Simulate the spreading of a disease by a SIR model . . . . .	817
Exercise E.42: Introduce problem and solver classes in the SIR model . . . . .	819
Exercise E.43: Introduce vaccination in a SIR model . . . . .	820
Exercise E.44: Introduce a vaccination campaign in a SIR model . . . . .	820
Exercise E.45: Find an optimal vaccination period . . . . .	821
Exercise E.46: Simulate human-zombie interaction . . . . .	821
Exercise E.47: Simulate a zombie movie . . . . .	823
Exercise E.48: Simulate a war on zombies . . . . .	824
Exercise E.49: Explore predator-prey population interactions . . . . .	824
Exercise E.50: Formulate a 2nd-order ODE as a system . . . . .	825
Exercise E.51: Solve $\ddot{u} + u = 0$ . . . . .	826
Exercise E.52: Make a tool for analyzing oscillatory solutions . . . . .	826
Exercise E.53: Implement problem, solver, and visualizer classes . . . . .	827
Exercise E.54: Use classes for flexible choices of models . . . . .	831
Exercise E.55: Apply software for oscillating systems . . . . .	831
Exercise E.56: Model the economy of fishing . . . . .	832